

ADLINK ROS 2 Solution

ADLINK
LEADING EDGE COMPUTING

NVIDIA PREFERRED PARTNER

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Table of Contents

The Future of AMRs is Open 03

Discover Our ROS 2 Robotic Controllers 04
Solution Stack 05
Accelerate Your Success with ADLINK ROS 2 Solution 06
Key Components of a Sensor Fusion System 07

Unleashing the Power of AMRs with ADLINK ROS 2 Solution 08
Next-Gen Logistics Automation - Forklift Robot 09
24/7 Automated Delivery Service - Delivery Robot 10
Effortless Lawn Care - Robotic Lawn Mower 11
Automated Safety Patrol - Security Robot 12
The Future of Public Transit - Autonomous Vehicle 13

Product Selection Guide 14

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The Future of AMRs Now Wide Open

The future of Automated Mobile Robots (AMRs) is now wide open, as they are due to revolutionize every sector. These intelligent machines can autonomously navigate and adapt to dynamic environments, performing tasks like material handling, package delivery, lawn mowing, and more. With proven value in enhancing productivity and safety, AMRs will become even smarter and more adaptable further down the road, expanding their applications to sectors beyond imaginable. Embrace AMRs and automation technologies, and you are in for a transformational treat in the coming years.





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Discover Our

ROS 2 Robotic Controllers

The robotic controller is crucial in enabling an AMR to operate independently. Since it has to combine sensor data, decision-making algorithms, and task execution logic to navigate, interact with its environment, and carry out assigned tasks efficiently and safely, its effectiveness directly impacts the AMR system's overall performance, reliability, and adaptability. Hence, ADLINK has created the ROScube, a highly versatile and modular ROS 2 robotic controller family, and here are the three main series of ROScube:



ROScube–Pico TGL

Compact robotic controller powered by Intel® CPU for quick and easy development

ROScube–X

AI robotic controller powered by NVIDIA® Jetson™ for real-time Sensor Fusion

ROScube–I

Intelligent robotic controller powered by Intel® CPU for complex data processing

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Solution Stack

The ROScube family is specially designed to seamlessly integrate with ROS 2 and its ecosystem.
This guarantees a smoother development process and improved synergy between hardware and software.

ROS 2 Robotic Controller
Hardware


RQX-59 Series


RQX-580/58G


NPN-1B/2B


RQP-T33/35/37


RQI-53/55/57/58

ROS 2
Software

AI Accelerator SDK
- Intel OpenVino
- NVIDIA TensorRT

ROS-Compatible Add-Ons & SDK
- Remote Control: EdgeGo
- Motion Control: SuperCat
- Protocol: Zenoh, Cyclone DDS
- Security: Trusted OS, TPM

Integrated Development Utilities
- NAV2
- MoveIt2
- GAZEBO
- RQT
- RQT_Graph
- RViz

OS – ROScube BSP - Ubuntu Linux Kernel

Partners

Solution Partners
FARobot, TIER IV, The Autoware Foundation

Sensor Partners
- Camera: TIER IV, StereoLabs*, eYeBrite, LEOPARD
- LiDAR: OUSTER

ADLINK's products and services

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Accelerate Your Success with ADLINK ROS 2 Solution

Benefits

We have years of experience in system and sensor integrations.

We are experts in edge AI platform and BSP customization.

Our strategic partnerships with leading sensor brands enable us to provide reliable robotic solutions.

Service Flow

In-depth discussion over project details and requirements

Recommending a suitable edge AI platform (robotic controller)

Customer testing and feedback

Quick PoC and implementation

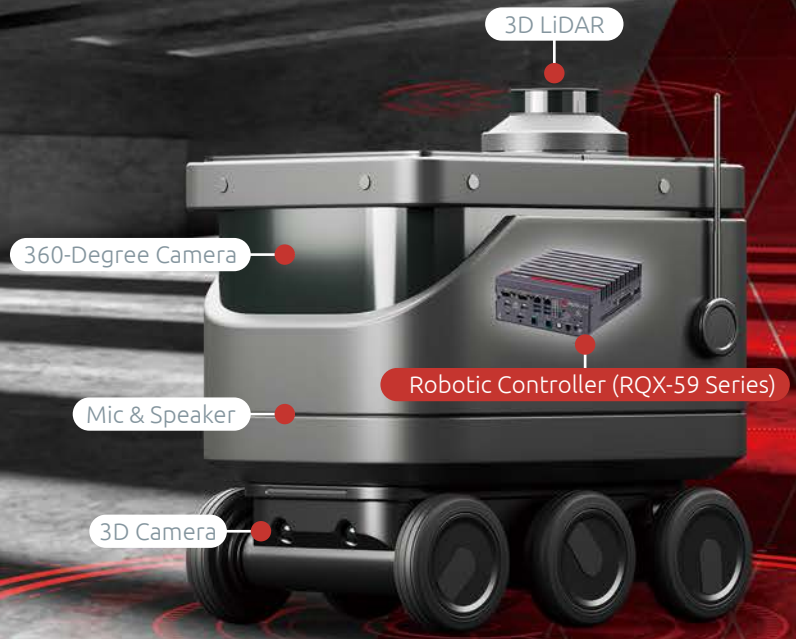
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Key Components of a Sensor Fusion System

A sensor fusion system combines data from multiple sensors to provide an accurate understanding of the environment.

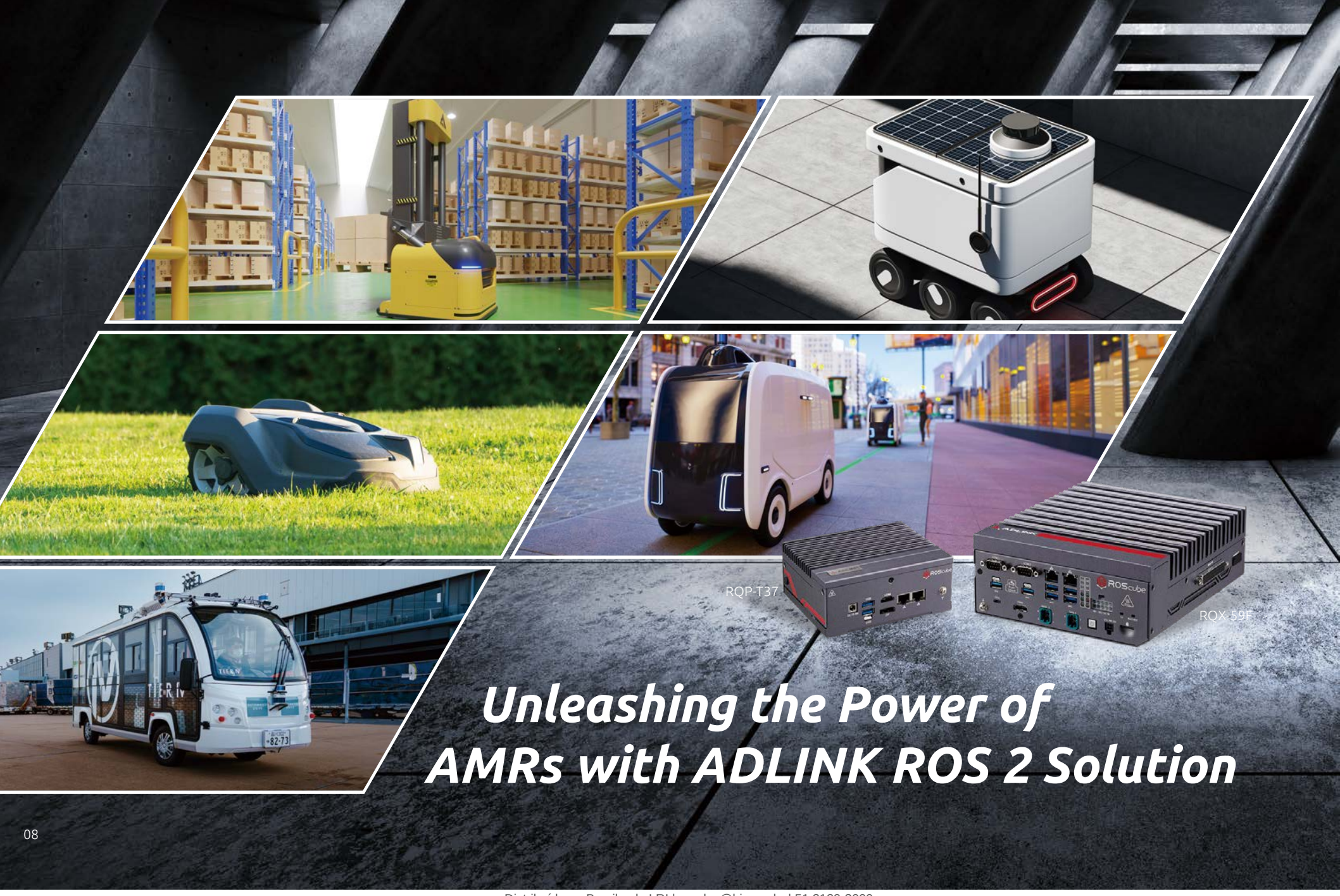
Key components of such a system include

- Crucial sensors: Cameras, LiDAR, radar, and more, capturing different types of data.
- Data preprocessing: Cleaning and organizing data for further processing.
- Sensor calibration: Ensuring proper alignment and synchronization.
- Sensor data fusion algorithms: Combining data and extracting valuable information using techniques such as Kalman filtering and particle filtering.
- Edge perception units and/or computational platforms: Effectively processing large amounts of data and flawlessly executing fusion algorithms.



ADLINK's ROScube robotic controller is known for its outstanding performance and power efficiency. The RQX-59 Series is the perfect edge perception system that offers Frame Sync for GMSL2 and FPD-Link III cameras, as well as customized BSPs. It has a comprehensive I/O interface and uses the Jetson AGX Orin module, designed to process sensor fusion data and execute fusion algorithms seamlessly.

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Unleashing the Power of AMRs with ADLINK ROS 2 Solution

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Forklift Robot

Challenges & Requirements

- Covering a wide geographic area and transporting heavy goods over long distances.
- Must maintain daily productivity with limited staff resources.

Solution & Insight

- ADLINK's RQX-59F can support various types of LiDAR and up to 8 FPD-Link III cameras. It processes sensor data in real-time and enables forklift robots to navigate safely in narrow spaces, even with big and heavy cargo.
- A forklift robot can do the work of several workers and never get tired, reducing labor costs yet improving work efficiency.

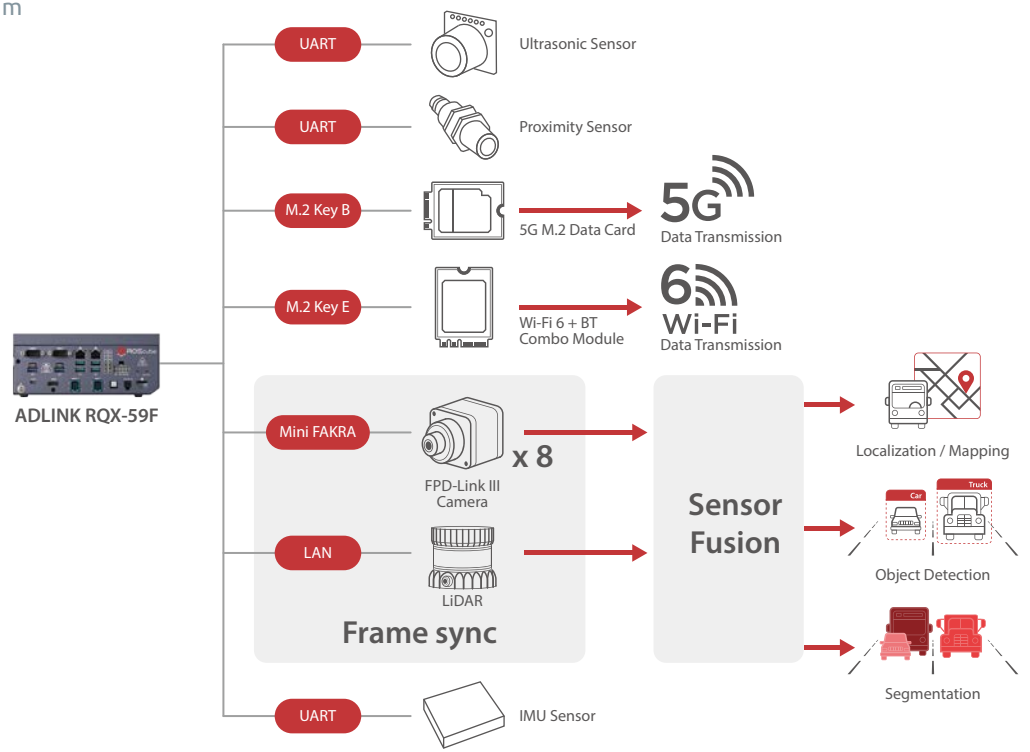
Use Case

Next-Gen Logistics Automation

Project Purpose

- Growing demand for smarter and more flexible AGV systems.
- AMRs offering efficient solutions amid rising labor costs.
- Minimizing workplace injuries caused by incorrect machine handling.

Diagram



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Delivery Robot

Challenges & Requirements

- Ensuring safe and reliable automated navigation in dynamic and unpredictable environments.
- Designing and integrating robust sensor systems for accurate perception and obstacle avoidance.

Solution & Insight

- ADLINK's RQX-59G supports the integration of various sensors, such as cameras and LiDAR, and effectively collects and processes sensor fusion data for reliable navigation and obstacle detection in dynamic environments.
- ADLINK's RQX-59G has a wide temperature operating range, ensuring performance and reliable operation in summer heat.

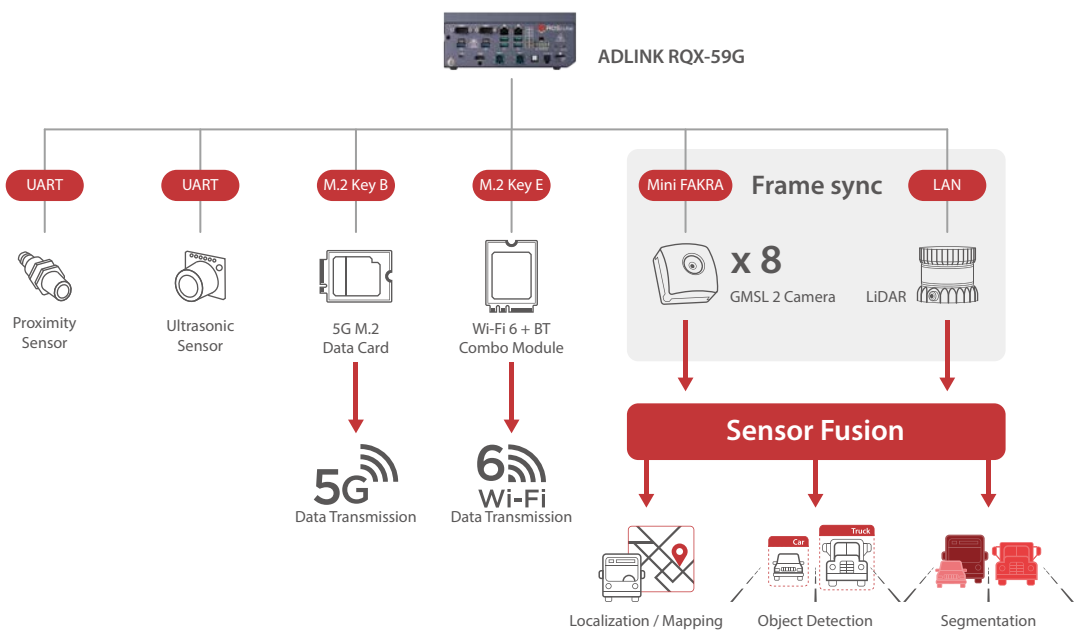
Use Case

24/7 Automated Delivery Service

Project Purpose

- Increasing demand for contactless, efficient delivery.
- Fulfilling 24/7 delivery services while addressing labor shortages in the delivery industry.
- Cost-effective alternative to traditional delivery services.

Diagram



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Robotic Lawn Mower

Challenges & Requirements

- A reliable edge AI platform to control the robot and process sensor data in real-time.
- 360-degree perception to navigate optimally through different terrains and environments.

Solution & Insight

- The RQX-59F with Jetson AGX Orin enhances the robotic mower's precision by detecting and avoiding obstacles through powerful AI performance.
- The RQX-59F supports up to 8 FPD-Link III cameras to ensure 360-degree image coverage, with internal IMU sensors also helping with navigation.

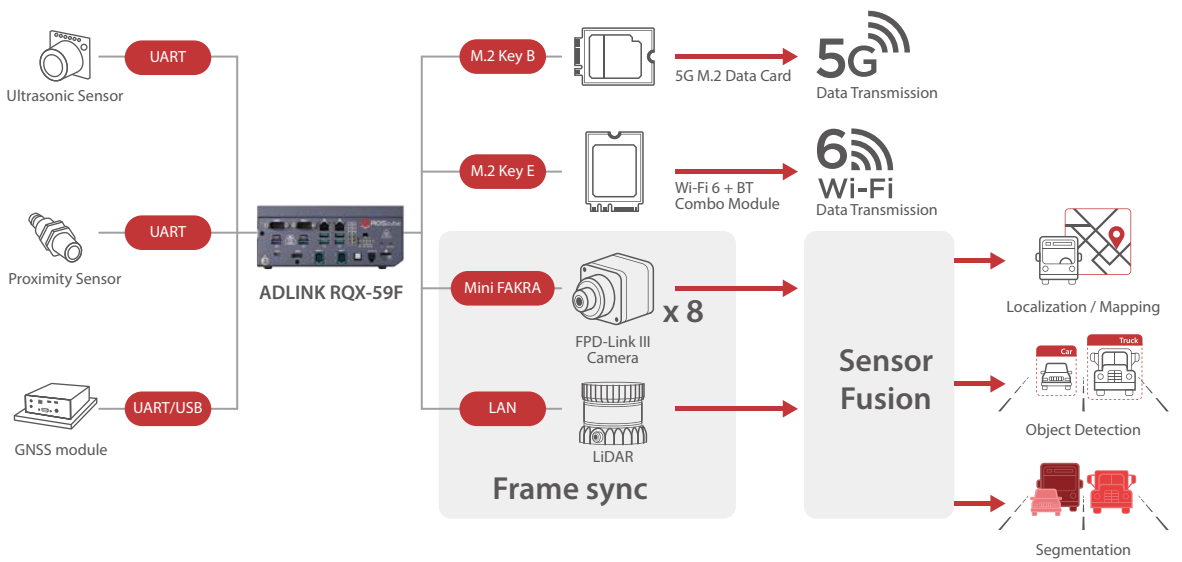
Use Case

Effortless Lawn Care

Project Purpose

- Robotic lawn mowers can be equipped with automated safety features for emergencies to prevent accidents and injuries caused by human errors.
- Effortless lawn maintenance and consistent results are achieved as the robotic mower handles cutting, trimming, and mulching, leading to a well-maintained lawn year-round.

Diagram



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Security Robot

Challenges & Requirements

- The robots should be able to issue visual, audio, and smoke warnings to suspicious individuals and apprehend perpetrators.
- The robot should be able to patrol public areas and address potential threats automatically. Plus, it should be able to react quickly.

Solution & Insight

- The RQP-T37 enables complex tasks like facial recognition and object detection and can also facilitate real-time data processing for quick decision-making.
- The RQP-T37 is a compact and energy-efficient device that significantly reduces power consumption in security robots.

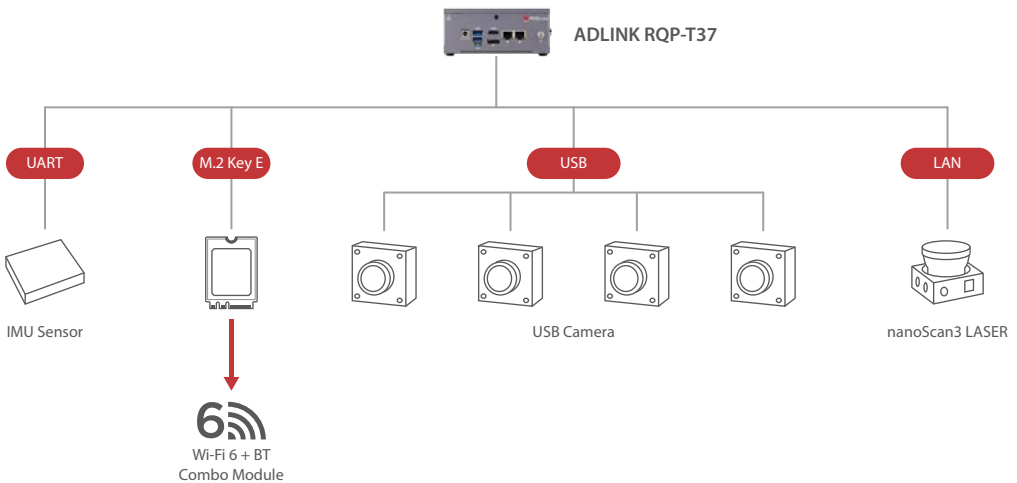
Use Case

Automated Public Safety Patrol

Project Purpose

- Security robots can be programmed to follow specific routes and protocols, ensuring reliable coverage without distractions or human errors.
- Security robots can handle real-time threats using the processed data received from various sensors, replacing human guards in hazardous environments.

Diagram



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Autonomous Vehicle

Challenges & Requirements

- Seamless integration of hardware and software components with robust middleware.
- Achieving precise synchronization between LiDAR and multiple automotive cameras is crucial.
- Advanced computing is necessary for safety measurements and monitoring.

Solution & Insight

- TIER IV has implemented an Edge Perception Development Kit for self-driving buses at airports and in crowded cities.
- The Edge Perception Development Kit includes ADLINK's ROScube RQX-58G controller and TIER IV's C1/C2 cameras.
- ADLINK's RQX-58G excels in supporting sensor fusion data processing and simultaneously supporting up to 8 automotive GMSL2 cameras.

Note: To learn more about the Edge Perception Development Kit, please visit: https://www.adlinktech.com/en/autonomous-driving-visual-perception-tier-iv. We highly recommend upgrading the RQX-58G to the latest RQX-59G model for 8X stronger AI performance with the Jetson Orin module.

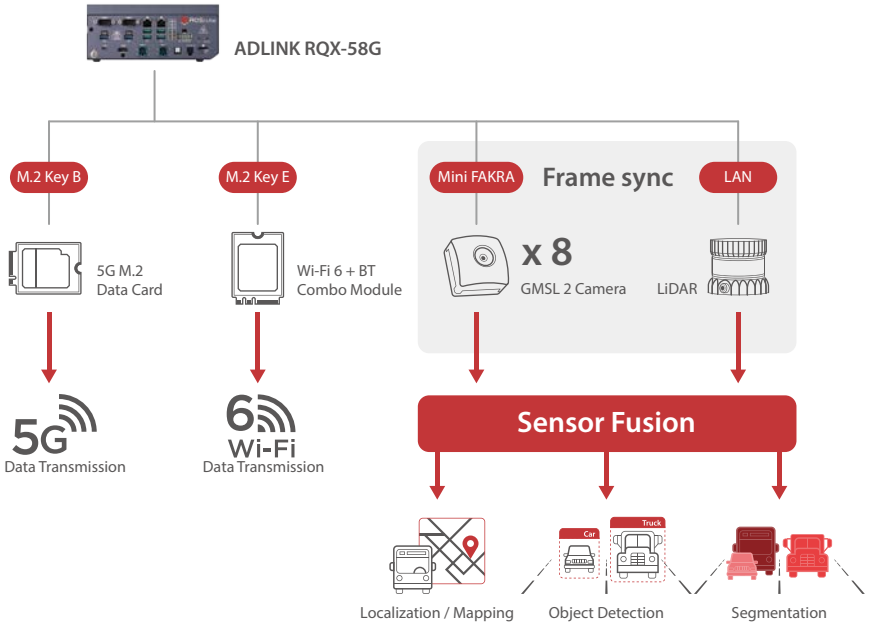
Use Case

The Future of Public Transit

Project Purpose

- Autonomous vehicles are equipped with advanced sensors and artificial intelligence, reducing human errors and accidents caused by distractions, fatigue, or impaired driving.
- Autonomous vehicles can communicate with each other and optimize traffic flow, leading to smoother and more efficient transportation systems.

Diagram



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Product Selection Guide



Model Name		RQX-59 Series		
NVIDIA® or Intel®		NVIDIA® Jetson AGX Orin™		
GMSL2 / FPD-Link III enabled		GMSL2 x 8 /FPD-Link III x 8		
Frame Sync and Time Sync		Yes		
Validated Sensors	Brands	GMSL2 Camera	FPD-Link III Camera	LiDAR
	TIER IV	Automotive HDR camera C1/C2	-	-
	StereoLabs	ZED-X/ ZED-X mini	-	-
	oToBrite	oToCAM264ISP	oToCAM264ISP oToCAM222 oToCAM251 (customized BSP)	-
	Leopard	LI-AR0233-GMSL2(non ISP)	-	-
	Ouster	-	-	OS1-32
OS		Jetpack 5.1.2 or above Ubuntu 20.04		
I/O		4x USB3.2; 2 x lockable USB3.2; 1x Micro USB (OTG); 2 x GbE		
Storage Device		1x M.2 Key M 2280 and 2242; 1x micro SD card slot		
Expansion		1x M.2 Key E 1630/2230 for Wi-Fi 6/BT; 1x M.2 Key B 3042/3052 for 5G/LTE		
Audio		Input/ Output		
CAN bus		CAN FD		
Dimensions (W x D x H)		190 x 210 x 80 mm, 7.48 x 8.27 x 3.149 in With expansion: 322 x 210 x 80 mm, 12.68 x 8.27 x 3.149 in		
Weight		3.4kg w/o expansion box 4.7kg w/ expansion box		

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Model Name		RQX-580/58G	
NVIDIA® or Intel®		NVIDIA® Jetson AGX Xavier™	
GMSL2 / FPD-Link III enabled		GMSL2 x 8	
Frame Sync and Time Sync		Yes	
Validated Sensors	Brands	GMSL2 Camera	LiDAR
	TIER IV	Automotive HDR camera C1/C2	-
	oToBrite	oToCAM264ISP	-
	Leopard	LI-AR0233-GMSL2 (non ISP)	-
	Ouster	-	OS1-32
OS		Jetpack 4.6 or above Ubuntu 18.04	
I/O		4x USB3.2; 2 x lockable USB3.2; 1x Micro USB (OTG); 2 x GbE	
Storage Device		1x M.2 Key M 2280 and 2242; 1x micro SD card slot	
Expansion		1x M.2 Key E 1630/2230 for Wi-Fi 6/BT; 1x mini PCIe socket for 4G/LTE	
Audio		Input/ Output	
CAN bus		CAN FD	
Dimensions (W x D x H)		190x 210x 80 mm (7.48 x 8.27 x 3.149 inch) With Expansion: 322 x 210 x 80 mm (12.68 x 8.27 x 3.149 inch)	
Weight		3.4kg w/o expansion box 4.7kg w/ expansion box	

Model Name		RQP-T33/35/37		RQI-53/55/57/58	
NVIDIA® or Intel®		11th Gen Intel® Core™ i7/i5/i3		8/9th Gen Intel® Core™ i7/i5/i3	
GMSL2 / FPD-Link III enabled		USB camera		USB camera	
Frame Sync and Time Sync		Yes		Yes	
Validated Sensors	Brands	USB camera	LiDAR	USB camera	LiDAR
	Intel®	RealSense™ Depth Camera D435	-	RealSense™ Depth Camera D435	-
	SICK	-	nanoScan3	-	nanoScan3
	Ouster	-	OS1-32	-	OS1-32
OS		Compatible with Ubuntu 20.04		Compatible with Ubuntu 20.04	
I/O		2x USB 3.2 Gen2 Type A port;2x USB 3.2 Gen2 Type C ports; COM 1: RS-232; COM 2: power management; 1x 1GbE, 1x 2.5GbE; 1x DP, 1x HDMI		4x GbE; COM 1/2: RS-232/422/485; 6 x USB 3.1 Gen 1 Type A; 4x USB 2.0 Type A	
Storage Device		1x M.2 Key-M for NVMe PCIe Gen4 x4 SSD		256GB mSATA SSD or 128GB mSATA SSD or 64GB mSATA SSD	
Expansion		1x M.2 Key-E 2230 for Wi-Fi		1 x Mini PCIe for CAN; 1 x Mini PCIe for WiFi or LTE; 1 x A+E key, 2230 for Wi-Fi	
Audio		Input/ Output		N/A	
CAN bus		N/A		CAN FD module (FARO-FP900) (optional)	
Dimensions (W x D x H)		140 x 110 x 63 mm		w/o expansion box: 210 x 240 x 86 mm; w/ expansion box: 210 x 240 x 165 mm	
Weight		1,086g		3.6kg w/o expansion box 4.6kg w/ expansion box	

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